

## CLAIMS

What is claimed is:

1. An automatic gain control comprising:
  - 5 a digital lowpass filter for filtering a series of digital samples generated by an analog-to-digital converter to generate a lowpass filtered digital sample series;
  - a power averager coupled to the digital lowpass
  - 10 filter for calculating an average power of the lowpass filtered digital sample series; and
  - a lookup table coupled to the power averager for setting a selectable gain of an amplifier coupled to the analog-to-digital converter as a function of the
  - 15 average power.

2. The automatic gain control of Claim 1 wherein the digital lowpass filter is an infinite impulse response digital lowpass filter.

3. The automatic gain control of Claim 2 wherein the infinite impulse response digital lowpass filter has a transfer function that may be expressed as:

$$H(z) = \frac{\sum_m b_m z^{-m}}{\sum_n a_n z^{-n}}$$

4. The automatic gain control of Claim 2 wherein the infinite impulse response digital lowpass
- 30 filter comprises:

a first sum function for receiving as input a series of digital samples and for generating a first sum;



average power within the dynamic range of the analog-to-digital converter.

[illegible]



8. A method for automatic gain control comprising the following steps:

amplifying a communications signal according to a  
5 selectable gain to generate an amplified communications  
signal;

digitizing the amplified communications signal to  
generate a series of digital samples representative of  
the amplified communications signal;

10 lowpass filtering the series of digital samples to  
generate a lowpass filtered digital sample series;

calculating an average power of the lowpass  
filtered digital sample series; and

15 setting the selectable gain of the amplifier as a  
function of the average power.

9. The method of Claim 8 wherein the step of  
lowpass filtering includes lowpass filtering by an  
infinite impulse response digital lowpass filter.

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10. The method of Claim 9 wherein the  
infinite impulse response digital lowpass filter has a  
transfer function that may be expressed as:

$$H(z) = \frac{\sum_m b_m z^{-m}}{\sum_n a_n z^{-n}}.$$

constant to go

put.

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11. The method of Claim 9 wherein the  
infinite impulse response digital lowpass filter  
comprises: 12. of lowpass fil  
half Nyquist

30 a first sum function for receiving as input a  
series of digital samples and for generating a first  
sum;

a first sum register coupled to the first sum  
function for storing the first sum;

a first unit delay coupled to the first sum register for delaying the first sum by one sample period to generate a first delayed sum;

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5 delay for delaying the first sum by two sample periods ;
  to generate a second delayed sum;
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10       a second multiplier coupled to the second unit  
      delay for multiplying the second delayed sum by a first  
      constant;

15        a second sum register coupled to the second sum  
function for storing the second sum;

20        a third sum register coupled to the third sum  
function for storing the third sum; and

25 output.

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General Information	
Project Name	...
Project Number	...
Project Manager	...
Project Status	...
Project Start Date	...
Project End Date	...
Project Budget	...
Project Funding	...
Project Location	...
Project Description	...
Project Objectives	...
Project Scope	...
Project Risks	...
Project Challenges	...
Project Success Factors	...
Project Lessons Learned	...
Project Recommendations	...
Project Conclusion	...